

Nm

## 90415 IRT

### Infrared Rotating Torque Sensor

- Measurement range 100 Nm to 27 kNm
- Max shaft speed 15000 rpm
- Non-linearity 0.05 %
- Output signal
  - Voltage (selectable)  $\pm 5$  V,  $\pm 10$  V,  $2.5$  V  $\pm 2.5$  V
  - Frequency (selectable) 60 kHz  $\pm 20$  kHz, 60 kHz  $\pm 30$  kHz, 10 kHz  $\pm 5$  kHz
- Current 4 ... 20 mA
- Supply voltage 12 VDC



The 90415 IRT (infrared rotating torque) sensor is based on our popular 01251 model, and now includes a dual signal output featuring one analog signal ( $\pm 5$  V,  $\pm 10$  V,  $2.5 \pm 2.5$  V or 4 ... 20 mA) and a frequency output (10 kHz  $\pm 5$  kHz, 60 kHz  $\pm 20$  kHz, or 60 kHz  $\pm 30$  kHz). All setup and configuration settings are completed through a very easy to use USB based GUI package and feature selectable outputs, filter settings and range settings. This sensor is designed for applications such as dynamometers and test stands where a high performance, high noise immunity, non-contact torque measurement is required.

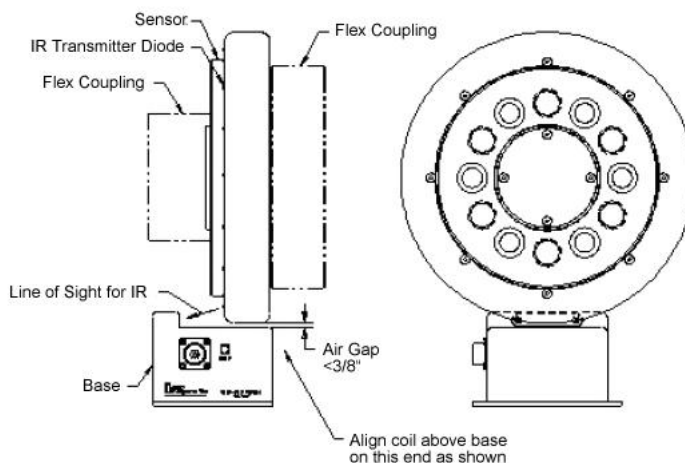
The rotating electronics of sensor are powered inductively. The rectified, regulated voltage is then sent to a strain gage bridge which senses applied torque. The signal is converted on-board the rotating torque sensor into digital format which is transmitted back to the base unit via IR diodes and receivers. Once captured by the receiver base, it is processed and converted back to the desired signal output.

#### FEATURES

- High frequency response and accuracy
- Voltage, current and frequency signal outputs
- No bearings or moving parts
- On-board shunt calibration
- Increased gap tolerance for the base unit
- Signal interrupt indication
- Single piece sensing element
- High immunity to signal noise
- No brush induced signal interference
- High operating RPM
- Custom flange configurations available
- Selectable digital filters down to 1Hz
- No pots or dip switches
- Software utility via USB interface
- Software allows for real-time data recording.
- Selectable output ranges.

#### DESIGN OPTIONS

- Thrust axis measurement
- Integral coupling features
- RPM and angle measurement
- On-board temperature measurement inputs





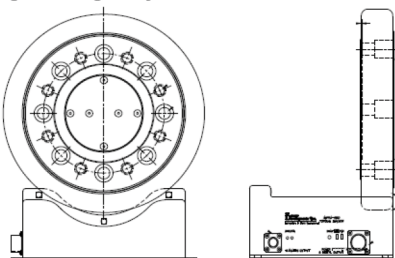
## SPECIFICATIONS

Parameter	
<b>Transmitter Electronics</b>	
Resolution:	16 bits
Accuracy:	0.01 % (Transmitter electronics only. Performance will depend highly on sensing element design. See calibration data sheet supplied for information on each sensor system.)
Sample Rate:	5000 samples/second
Filter:	4-pole Butterworth low pass @ 1000 Hz
Power Input:	Provided by base
Temperature Range:	-20 ... +85 °C
Temperature Drift:	0.005 %/K max.
<b>Receiver Base</b>	
Resolution:	16 bits
Accuracy:	0.01 %
Analog Output Voltage (selectable):	±5 V, ±10 V, 2.5 V ±2.5 V
Frequency Output (selectable):	60 kHz ±20 kHz, 60 kHz ±30 kHz, 10 kHz ±5kHz
Analog Output Current:	12 mA ±8 mA (4 ... 20 mA)
External Shunt Inputs (3):	5 VDC @ 2mA to 24 VDC @ 12 mA
Power Input:	12 VDC ±5 % @ 4 A (120 VAC to 12 VDC @ 4A power supply is included)
Error Relay Contact Rating:	500 mA, 24 VDC max.
Error Relay contact Type:	SPDT close to error
Temperature Range:	-20 ... +70 °C
Temperature Drift:	0.005 %/K max.
<b>Typical Sensor Performance</b>	
Accuracy:	0.05 % FS
Maximum RPM:	15000
Compensated Temperature:	+20 ... +70 °C
Useable Temperature:	-20 ... +70 °C
Temperature Effect on Zero:	0.0035 % of FS/°F
Temperature Effect on Span:	0.0035 % of rdg./°F
Full-scale Ranges:	1 k to 240 kin lbs (100 Nm to 27 kNm)

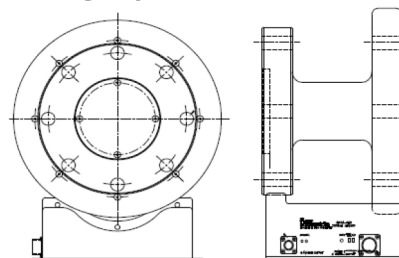
## TYPICAL SENSOR CONFIGURATIONS

Please contact us for specific drawings and capacities.

**Single Flange Style:**



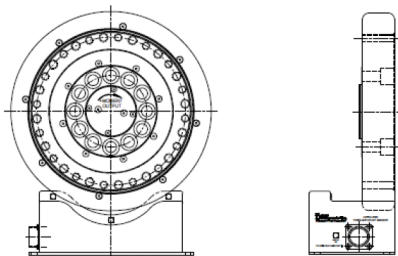
**Dual Flange Style:**



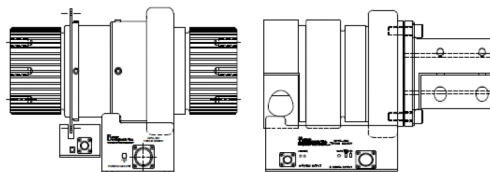


## TYPICAL SENSOR CONFIGURATIONS

### Torque and Thrust Style:



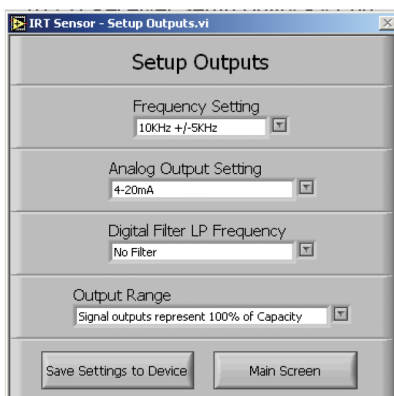
### Custom Interfaces:



## GUI SOFTWARE INTERFACE

### Setup Signal Outputs:

Configure the type of signal outputs you would like; frequency (3 types) or Analog (3 types). Also configure the low pass filter setting and the desired output range.



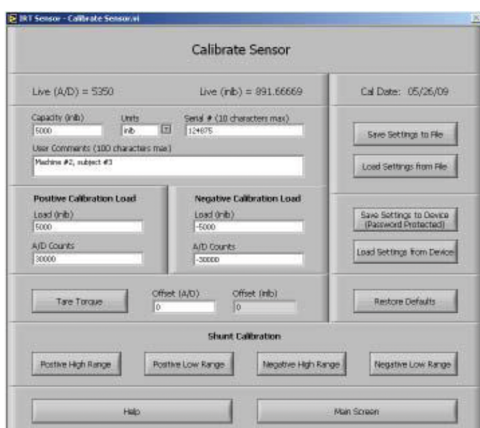
### Main Display Screen:

This screen will display the live readings being acquired by the torque sensor. Use this screen to see if your setup is performing as desired and to provide a real time numerical display. Data recording is also triggered from this screen.



### Calibration Setup:

This screen allows the operator to view the current sensor calibration values, as well as conduct a new calibration.



### Data Recording Screen:

This screen is displayed when the operator begins storing data via the USB connection. It provides a real time display of the data being stored. The stored data can also be viewed in a similar manner.

