





P530 Rotary Sensor

FEATURES

- Non-contacting inductive technology to eliminate wear
- Angle set to customer's requirement
- Compact, durable and reliable
- High accuracy and stability
- Sealing to IP67

As a leading designer and manufacturer of linear, rotary, tilt and intrinsically safe position sensors, we has the expertise to supply a sensor to suit a wide variety of applications. Our P530 is an affordable, durable, highaccuracy rotary sensor designed for industrial and scientific feedback applications.

The P530, is supplied with the output calibrated to the angle required by the customer, up to 360 degrees, with full EMC protection built in. The sensor provides a linear output proportional with input shaft rotation. There is a machined registration mark to identify the calibrated mid point.

It is particularly suitable for OEMs seeking good sensor performance for arduous applications such as industrial machinery where cost is important.

Overall performance, repeatability and stability are outstanding over a wide temperature range. The P530 has long service life and environmental resistance with a rugged stainless steel body and shaft, it also offers a range of mechanical and electrical options. The flange mount makes the sensor easy to install. Environmental sealing is to IP67.

Do you need a position sensor made to order to suit a particular installation requirement or specification? We'll be happy to modify any of our designs to suit your needs - please contact us with your requirements.



SPECIFICATION

Dimensions				
Body diameter	35 mm			
For full mechanical details see drawing P530-11				
Independent Linearity	≤ ± 0.25% FSO @ 20°C			
Temperature Coefficients	< ± 0.01%/°C Gain & < ± 0.01%FS/°C Offset			
Frequency response	> 10 kHz (-3dB) > 300 Hz (-3dB) 2 wire 4 to 20 mA			
Resolution	Infinite			
Noise	< 0.02% FSO			
Torque	< 20 mNm Static			
Environmental Temperature Limits	Operating -40°C to +125°C standard /-20°C to +85°C buffered Storage -40°C to +125°C			
Sealing	IP67			
EMC Performance	EN 61000-6-2, EN 61000-6-3			
Vibration	IEC 68-2-6: 10 g			
Shock	IEC 68-2-29: 40 g			
MTBF	350,000 hrs 40°C Gf			
Drawing List	P530-11 / Sensor Outline			
3D models, step or .igs format, a	vailable on request			





High-resolution angle feedback for industrial and scientific applications

LONGER SERVICE LIFE THANKS TO TECHNOLOGY

Our displacement transducers Displacement transducers have the simplicity of a potentiometer with the durability of an LVDT/RVDT.

Our technology combines the best of basic inductive inductive principles with advanced microelectronic integrated integrated circuit technology. The sensor, which is based on simple inductive coils with ASIC control technology, directly measures the absolute position and provides a DC analogue output signal. As there is no contact between moving electrical components, reliability is high and wear and tear is and wear is eliminated, resulting in an exceptionally long service life.

Our technology overcomes the disadvantages of LVDT technology - bulky coils, poor length-to-stroke ratio and the need for the need for special magnetic materials. It does not require separate signal conditioning. We also offer a range of ATEX-qualified, intrinsically safe sensors. sensors.We also offer a range of ATEX-qualified intrinsically-safe sensors.

TABLE OF OPTIONS

CALIBRATED TRAVEL: Factory-set to any angle from ±50° to ±180° in increments of 1 degree.

Full 360° Mechanical rotation.

ELECTRICAL INTERFACE OPTIONS

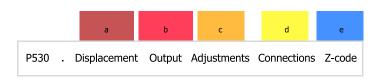
OUTPUT SIGNAL Standard:	SUPPLY INPUT	OUTPUT LOAD	
0.5-4.5V dc ratiometric Buffered:	$+5V$ dc nom. \pm 0.5V.	5k! min.	
0.5-4.5V dc ±5V dc 0.5-9.5V dc ±10V dc	+24V dc nom. + 9-28V. ±15V dc nom. ± 9-28V. +24V dc nom. + 13-28V. ±15 V dc nom. ± 13.5-28V.	5k! min. 5k! min. 5k! min. 5k! min.	
Supply Current	10mA typical, 20mA maximum.		
4-20mA (2 wire) (3 wire sink) (3 wire source)	+24 V dc nom. + 18-28V. +24 V dc nom. + 13-28V. +24 V dc nom. + 13-28V.	300! @ 24V. 950! @ 24V. 300! max.	

Sensor's supplied with access to output 'zero' and 'span' calibration adjustments as standard. No access option available.

CONNECTOR/CABLE OPTIONS

Connector - M12 4 pin IP67 Cable with M12 gland or short gland IP67 Cable length >50 cm – please specify length in cm

ORDERING OPTIONS

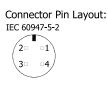


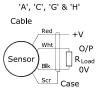
a Displacement (degrees) Valu					
Displacement in degrees	e.g. 0 - 270 degrees	270			
b Output					
Supply V dc V₅ (tolerance)	Output	Code			
+5V (4.5 - 5.5V)	0.5 - 4.5V (ratiometric with supply)	Α			
±15V nom. (±9 - 28V)	±5V	В			
+24V nom. (13 - 28V)	0.5 - 9.5V	С			
±15V nom. (±13.5 - 28V)	±10V	D			
+24V nom. (18 - 28V)	4 - 20mA 2 wire	E			
+24V nom. (13 - 28V)	4 - 20mA 3 wire Sink	F			
+24V nom. (9 - 28V)	0.5 - 4.5V	G			
+24V nom. (13 - 28V)	4 - 20mA 3 wire Source	Н			
c Calibration Adjustments Code					
Accessible - default		blank			
Sealed		Y			
Scaled		•			
d Connections Cable or C	Connector	Code			
d Connections Cable or C	Connector IP67 M12 IEC 60176-2-101 plastic				
		Code			
d Connections Cable or C	IP67 M12 IEC 60176-2-101 plastic	Code			
d Connections Cable or Connector Cable Gland	IP67 M12 IEC 60176-2-101 plastic pre-wired	Code J Jxx			
d Connections Cable or Connector Cable Gland Cable Gland	IP67 M12 IEC 60176-2-101 plastic pre-wired IP67 IP67 Short in cm. e.g. L2000 specifies cable gland with 20 m	Code J Jxx Lxx Mxx			

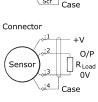


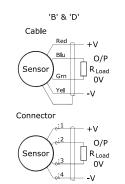
INSTALLATION INFORMATION

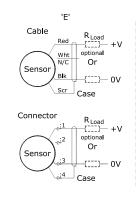
Output Option	Output Description:	Supply Voltage: V_s (tolerance)	Load resistance: (include leads for 4 to 20mA O/Ps)
Α	0.5 - 4.5V (ratiometric with supply)	+5V (4.5 - 5.5V)	5k!
В	±5V	±15V nom. (±9 - 28V)	5k!
С	0.5 - 9.5V	+24V nom. (13 - 28V)	5k!
D	±10V	±15V nom. (±13.5 - 28V)	5k!
E	4 - 20mA 2 wire Current Loop	+24V nom. (18 - 28V)	# 0 - 300! max. @24V ~ 1.2 to 6V across 300! $\{R_L \text{ max.} = (V_s - 18) / 20^{-3}\}$
F	4 - 20mA 3 wire Sink	+24V nom. (13 - 28V)	# 0 - 950! max. @24V ~ 3.8 to 19V across 950! $\{R_L \text{ max.} = (V_s - 5) / 20^{-3}\}$
G	0.5 - 4.5V	+24V nom. (9 - 28V)	5k!
н	4 - 20mA 3 wire Source	+24V nom. (13 - 28V)	# 0 - 300! max. ~ 1.2 to 6V across 300!

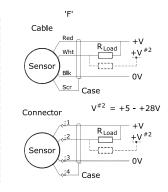




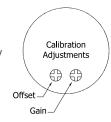




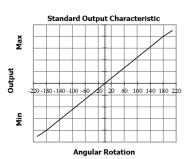




GAIN AND OFFSET ADJUSTMENT: (Where accessible - Typically \pm 10% Min available) To adjust the gain or offset use a small potentiometer adjuster or screwdriver 2mm across. Do not apply too much force on the potentiometers. The offset is set at mid span at the mid point, within \pm 5°, of rotation.



- MECHANICAL MOUNTING: Flange mounted, via two slots 4.5mm by 30 degrees wide on a 48mm pitch. The sensor should be mounted with minimal axial and radial loading on the shaft for optimum life. It is recommended that the shaft is coupled to the drive using a flexible coupling, recommended maximum axial load 1kg. Tests indicate that life in excess of 16 million cycles can be achieved with 1kg side and end load.
- **OUTPUT CHARACTERISTIC:** The sensor has $\pm 220^\circ$ mechanical rotation around the mid point. At the mid point the output signal will be half full scale deflection, the shaft flat will be aligned with the registration mark in the base of the sensor $\pm 5^\circ$. In the ut increases as the shaft is rotated in an anti-clockwise direction viewed from the shaft. The calibrated range is factory set, to between 100 and 360°.

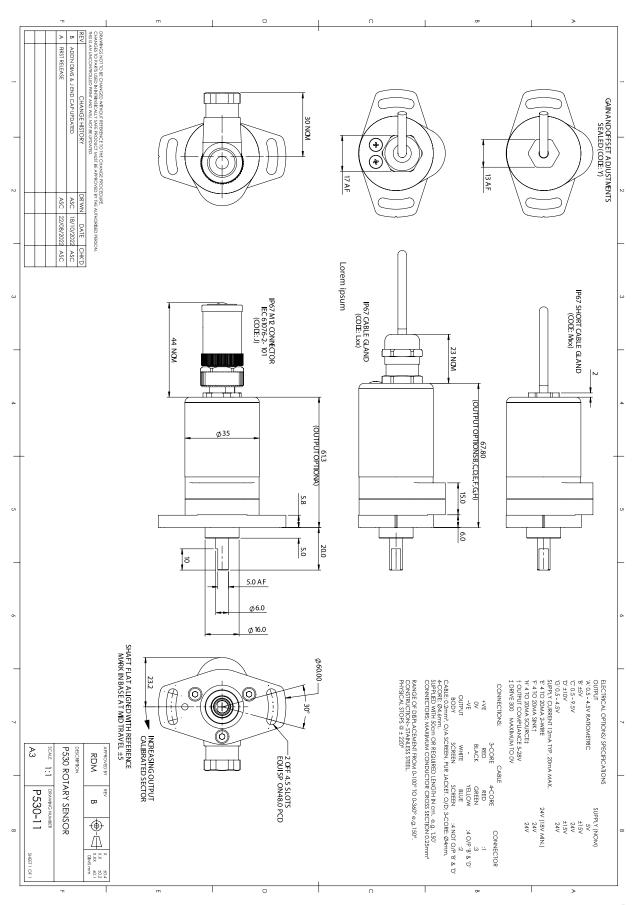


INCORRECT CONNECTION PROTECTION LEVELS:

- A Not protected the sensor is not protected against either reverse polarity or over-voltage.
 The risk of damage should be minimal where the supply current is limited to less than 50mA.
- B & D Supply leads diode protected. Output must not be taken outside ± 12V.
- C & G Supply leads diode protected. Output must not be taken outside 0 to 12V.
- E, F & H Protected against any misconnection within the rated voltage.







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The information provided herein is to the best of our knowledge true and accurate, it is provided for guidance only. All specifications are subject to change without prior notification.

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