





## P111

# Rugged Stand-Alone Linear Position Sensor

## **FEATURES**

- Non-contacting inductive technology to eliminate wear
- Travel set to customer's requirement
- Compact and self-contained
- High durability and reliability

tally, and supported between rod eyes.

High accuracy and stability



It remains an affordable, durable, high-accuracy position sensor designed for industrial and scientific feedback applications. The unit is highly compact and spaceefficient, being responsive along almost its entire length. Like all sensors, the P111 provides a linear output proportional to travel.

or there is a need for longer travel sensors, mounted horizon-

Each sensor is supplied with the output calibrated to the travel required by the customer, any stroke from 0-5mm to 0 -800mm and with full EMC protection built in. The sensor is very robust, the body and push rod being made of stainless steel for long service life and environmental resistance. It is particularly suitable for OEMs seeking good sensor performance for arduous applications such as industrial machinery where cost is important.

Overall performance, repeatability and stability are outstanding over a wide temperature range. The sensor is easy to install with mounting options including M8 rod eye bearings and body clamps. The push rod can be supplied free or captive, with female M8 thread, an M8 rod eye, or dome end. Captive push rods can be sprung loaded, in either direction, on sensors up to 300mm of travel.

The P111 also offers a wide range of mechanical and electrical options, environmental sealing is to IP65 or IP67, depending on cable/connector options.



## SPECIFICATION

#### Dimensions

Body diameter 35 mm

Body length (Axial version) Body length (Radial version) calibrated travel + 163 mm

Body length (Radial version) calibrated travel + 186 mm
Push rod extension calibrated travel + 7 mm, 0D 12.6 mm
For full mechanical details see drawing P111-11

Independent Linearity  $\leq$  ± 0.25% FSO @ 20°C - up to 450 mm

 $\leq$  ± 0.5% FSO @ 20°C - over 450 mm  $\leq$  ± 0.1% FSO @ 20°C \* available upon request.

\*Sensors with calibrated travel from 10 mm up to 400 mm.

< ± 0.01%/°C Gain & Temperature Coefficients

<  $\pm$  0.01%FS/°C Offset

Frequency Response

> 10 kHz (-3dB) > 300 Hz (-3dB) 2 wire 4 to 20 mA

Resolution Infinite Noise < 0.02% FS0

Environmental Temperature Limits

-40°C to +125°C standard Operating -20°C to +85°C buffered -40°C to +125°C Storage

Sealing IP65/IP67 depending on connector / cable option

EMC Performance EN 61000-6-2, EN 61000-6-3

Vibration IEC 68-2-6: 10 g Shock IEC 68-2-29: 40 a **MTBF** 350,000 hrs 40°C Gf

Drawing List

Sensor Outline P111-11

Drawings, in AutoCAD® dwg or dxf format, available on request.

Do you need a position sensor made to order to suit a particular installation requirement or specification? We'll be happy to modify any of our designs to suit your needs - please contact us with your requirements.



# How PIPS® technology eliminates wear for longer life

The PIPS® technology is a major advance in displacement sensor design. PIPS®-based displacement transducers have the simplicity of a potentiometer with the life of an LVDT/RVDT

PIPS® technology combines the best in fundamental inductive principles with advanced micro-electronic integrated circuit technology. A PIPS® sensor, based on simple inductive coils using ASIC control technology, directly measures absolute position giving a DC analogue output signal. Because there is no contact between moving electrical components, reliability is high and wear is eliminated for an exceptionally long life.

PIPS® overcomes the drawbacks of LVDT technology – bulky coils, poor length-to-stroke ratio and the need for special magnetic materials. It requires no separate signal conditioning.

Our LIPS® range are linear sensors, while RIPS® are rotary units and TIPS® are for detecting tilt position. Ask us for a full technical explanation of PIPS® technology.

We also offer a range of ATEX-qualified intrinsicallysafe sensors.

## TABLE OF OPTIONS

**CALIBRATED TRAVEL:** Factory set to any length from 0-5mm to 0-800mm (e.g. 254mm)

#### **ELECTRICAL IN TERFACE OPTIONS**

OUTPUT SIGNAL	SUPPLY INPUT	OUTPUT LOAD
Standard: 0.5-4.5 V dc ratiometric	+5 V dc nom. ± 0.5V.	5kΩ min.
Buffered: 0.5-4.5 V dc ± 5V dc 0.5-9.5 V dc ± 10 V dc	+24V dc nom. + 9-28V. ±15V dc nom. ± 9-28V. +24V dc nom. + 13-28V. ±15 V dc nom. ± 13.5-28V.	$5k\Omega$ min. $5k\Omega$ min. $5k\Omega$ min. $5k\Omega$ min.
Supply Current	10 mA typical, 20mA maximum.	
4-20mA (2 wire) (3 wire sink) (3 wire source)	+ 24 V dc nom. + 18-2 8V. + 24 V dc nom. + 13-2 8V. + 24 V dc nom. + 13-2 8V.	$300\Omega$ @ 24V. $950\Omega$ @ 24V. $300\Omega$ max.

Axial sensors supplied with access to output 'zero' and 'span' calibration adjustments as standard. No access option available.

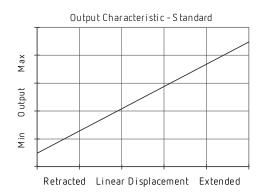
#### CONNECTOR/CABLE OPTIONS

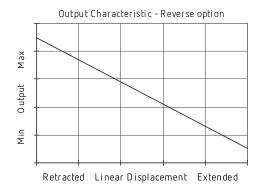
Connector - Hirschmann GD series Axial, IP65 Connector - Hirschmann ELWIKA 410 2 Radial, IP67 Cable with M12 gland or short gland Axial, IP67 Cable with Pg 9 gland Radial, IP67 Cable length >5 0 cm - please specify length in cm

#### MOUNTING OPTIONS

M8 rod eye bearing ( radial versions), Body Tube Clamp  $\!\!\!/\!\!\!\!/s$  (axial or radial versions).

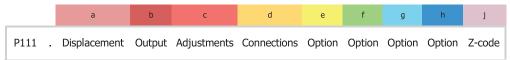
 ${\bf PUSH~ROD~OPTIO~NS}~$  –standard retained with M8x1.25 female thread, M8 rod eye bearing, Dome end, Sprung loaded (retraction or extension) or Free.







# HOW TO ORDER



a Displacement (mm)		Value
Displacement in mm	e.g. 0 - 254 mm	254
b <b>Output</b>		
Supply V dc <sub>Vs</sub> (tolerance)	Output	Code
+5V (4.5 - 5.5V)	0.5 - 4.5V (ratiometric with supply)	Α
±15V nom. (±9 - 28V)	±5V	В
+24V nom. (13 - 28V)	0.5 - 9.5V	С
±15V nom. (±13.5 - 28V)	±10V	D
+24V nom. (18 - 28V)	4 - 20mA 2 wire	E
+24V nom. (13 - 28V)	4 - 20mA 3 wire Sink	F
+24V nom. (9 - 28V)	0.5 - 4.5V	G
+24V nom. (13 - 28V)	4 - 20mA 3 wire Source	Н
c Calibration Adjustn	nents	Code
Accessible - default <sup>†</sup>	†Axial body style only. Radial body	blank
Sealed	style sealed by default.	Y
d Connections Cable* or	Connector	Code
Cable Gland - Radial	IP67 Pg9	Ixx
Connector - Axial	IP65 DIN 43650 'C'	J
Connector - Radial	IP67 M12 IEC 60947-5-2	K
Cable Gland - Axial	IP67 M12	Lxx
Cable Gland - Axial	IP67 Short	Mxx
*Supplied with 50 cm as standard specifies cable gland with 20 met	, specify required cable length specified in cm. e.qres of cable. Nb: restricted cable pull strength.	g. L2000
e Body Fittings		Code
None - default		blank
M8 Rod-eye Bearing	Radial body style only	N
Body Clamps - 1 pair		P
Body Clamps - 2 pairs		P2
f Sprung Push Rod		Code
None - default		blank
Spring Extend	Up to 300mm displacement.	R
Spring Retract	Captive push rod only.	S
g Push Rod Fittings		Code
None - default	Female Thread M8x1.25x12 deep	blank
Dome end	Required for option 'R'	Т
M8 Rod-eye Bearing		U
h Push Rod Options		Code
Captive - default	Push rod is retained	blank
Non-captive	Push rod can depart body	V

j <b>Z-code</b>	Code
Connector IP67 M12 IEC 60947-5-2 must have options 'Y' & 'J'	Z600
Connector IP67 M12 IEC 60947-5-2 must have option 'J'	Z601
$\leq \pm 0.1\%$ @20°C Independent Linearity displacement between 10mm & 400mm only!	Z650
Connector with cable option 'J' or 'K' with length required in cm i.e. J100 specifies connector with 100cm of cable.	Z999

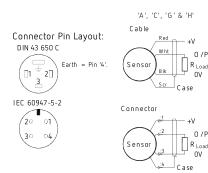


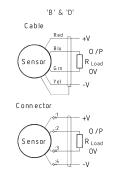


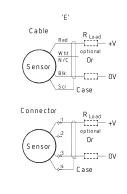
## INSTALLATION INFORMATION

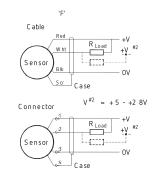
Output Option	Output Description:	Supply Voltage: V <sub>s</sub> (tolerance)	<b>Load resistance:</b> (include leads for 4 to 20mA 0 /Ps)
А	0.5 - 4.5V (ratiometric with supply)	+ 5V (4.5 - 5.5V)	≥ 5kΩ
В	± 5V	±15V nom. (±9 - 28V)	≥ 5kΩ
С	0.5 - 9.5V	+ 24V nom. (13 - 28V)	≥ 5k Ω
D	±10V	±15V nom. (±13.5 - 28V)	≥ 5k Ω
E	4 - 20mA 2 wire Current Loop	+ 24V nom. (18 - 28V)	$\approx 0$ – 300 $\Omega$ max. (e) 24V $\sim 1.2$ to 6V across 300 $\Omega$ {R $_L$ max. = (V $_s$ – 18) $/$ 20 $^{-3}$ }
F	4 - 20mA 3 wire Sink	+ 24V nom. (13 - 28V)	≈ 0 - 950 $\Omega$ max. @ 24V ~ 3.8 to 19V across 950 $\Omega$ {R <sub>L</sub> max. = (V <sub>s</sub> - 5) / 20 <sup>-3</sup> }
G	0.5 - 4.5V	+ 24V nom. (9 - 28V)	≥ 5kΩ
Н	4 - 20mA 3 wire Source	+24V nom. (13 - 28V)	≈ $0$ - $300\Omega$ max. ~ 1.2 to 6V across $300\Omega$

Not all output options available - see product datasheet for full options list









Gain and Offset Adjustment: (Where accessible - Typically ± 10% Min available) To adjust the gain or offset use a small potentiometer adjuster or screwdriver 2mm across. Do not apply too much force on the potentiometers.

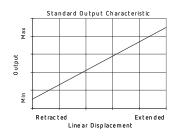
Calibration Adjustments 0 0

Mechanical Mounting: Depending on options; Body can be mounted by M8 rod eye or by clamping the sensor body - body clamps are available, if not already ordered. Target by M8x1.25 female thread or M8 rod eye. It is assumed that the sensor and target mounting points share a common earth.

Output Characteristic: Target is extended 7 mm from end of body at start of normal travel. The output increases as the target extends from the sensor body, the calibrated stroke is between 5 mm and 800 mm.

Warning - The M12 IEC 60947 connector may be rotated for purposes of convenient orientation of the connector and cable, however rotating the connector more than one

complete revolution is not recommended. Repeated rotation of the connector will damage the internal wiring!



Incorrect Connection Protection levels:-

Not protected — the sensor is not protected against either reverse polarity or over-voltage. The risk of Α damage should be minimal where the supply current is limited to less than 50mA.

Supply leads diode protected. Output must not be taken outside ± 12V. Supply leads diode protected. Output must not be taken outside 0 to 12 V. B & D C & G E, F & H Protected against any misconnection within the rated voltage.







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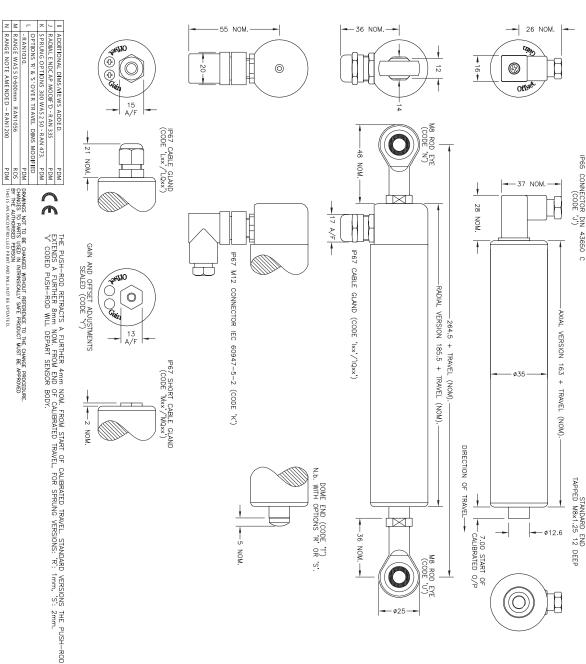
The information provided herein is to the best of our knowledge true and accurate, it is provided for guidance only. All specifications are subject to change without prior notification.





N.b. ROD-EYE ORIENTATION NOT GUARANTEED.

# **ELECTRICAL OPTIONS / SPECIFICATIONS**



SPRI		°	FORCE (N)	GAIN AND OFFSE RADIAL BODY, CO
SPRING FORCE V STROKE (CODE 'R' OR 'S')	STROKE (mm)	50 100 200 250 300	zą vą	GAIN AND OFFSET ADJUSTMENTS NOT AVAILABLE WITH RADIAL BODY, CODE 'Ixx' AND 'K', OPTIONS.

SINGLE PAIR OF BODY CLAMPS 'P'
THO PAIRS OF BODY CLAMPS 'P2'
SPRING RETURN PUSH-ROD, TRAVEL \$300mm
RETURN TO EXTENDED POSITION (CODE 'R')
RETURN TO RETRACTED POSITION (CODE 'S')

PUSH-ROD FREE (CODE 'V') - NOT AVAILABLE WITH SPRUNG OPTIONS.

\*CONNECTORS; MAXIMUM CONDUCTOR CROSS SECTION 0.75mm² RANGE OF DISPLACEMENT FROM 0-5mm TO 0-800mm e.g.76, IN INCREMENTS OF 1mm.

BODY MATERIAL: STAINLESS STEEL FURTHER OPTIONS:

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1	m		N 29/08/17	9/11/15	28/07/15	08/04/14	08/03/13	00/0///
SHEET [] OF []	DRAWING P111-11 REV N	POSITION SENSOR	STAND ALONE LINEAR	P 111 LIPS RU GGED	DESCRIPTION		(b) (c) PDM (x,xx ±0.1	) 010000