

# **P502 Small Angle Rotary Sensor**High-resolution angle feedback for hydraulic and pneumatic cylinders



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P502

#### APPLICATION

- Non-contacting inductive technology to eliminate wear
- Angle set to customer's requirement
- Compact, durable and reliable
- High accuracy and stability
- Sealing to IP65/IP67 as required



As a leading designer and manufacturer of linear, rotary, tilt and intrinsically safe position sensors, Althen has the expertise to supply a sensor to suit a wide variety of applications. Our P502 is an affordable, durable, high-accuracy rotary sensor designed for industrial and scientific feedback applications, like the P500 but with better resolution at smaller angles of deflection.

The P502, like all Althen sensors, provides a linear output proportional with angle of rotation. Each unit is supplied with the output calibrated to the angle required by the customer, between 5 and 15 degrees and with full EMC protection built in. The sensor provides a linear output proportional with input shaft rotation, which has full 360 degree rotational freedom. There is a machined registration mark to identify the calibrated mid point. It is particularly suitable for OEMs seeking good sensor performance for arduous applications such as industrial machinery where cost is important.

Overall performance, repeatability and stability are outstanding over a wide temperature range. The P502 has long service life and environmental resistance with a rugged stainless steel body and shaft, the flange and servo mounts are anodised aluminium. The flange or servo mounting options make the sensor easy to install, it also offers a range of mechanical and electrical options. Environmental sealing is to IP65 or IP67 depending on selected cable or connector options.

#### SPECIFICATIONS

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Dimensions <sup>1</sup>			
Body diameter	35 mm		
Body Length (to seal face)	44 mm standard, 50 mm buffered		
Shaft	15 mm Ø 6 mm		
Independent Linearity	≤ ± 0.25% FSO @ 20°C		
Temperature Coefficients	< ± 0.01%/°C Gain & < ± 0.01%FS/°C Offset		
Frequency Response	> 10 kHz (-3dB) > 300 Hz (-3dB) 2 wire 4 to 20 mA		
Decelution	Infinite	-	
Resolution	Infinite	_	
Noise	< 0.02% FSO		
Torque	< 20 mNm Static		
Environmental Temperature Limits			
Operating	-40°C to +125°C standard		
	-20°C to +85°C buffered		
Storage	-40°C to +125°C	_ 5	
Sealing	IP65/IP67 depending on connector / cable option		
EMC Performance	EN 61000-6-2, EN 61000-6-3		
Vibration	IEC 68-2-6: 10 g	06 2025   version 0001	
Shock	IEC 68-2-29: 40 g		
МТВБ	350,000 hrs 40°C Gf		



# SPECIFICATIONS (CONTINUED)

Drawing List <sup>2</sup>			
P502-11	Sensor Outline		
<sup>1</sup> For full mechanical details see drawings P502-11 <sup>2</sup> 3D models, step or .igs format, available on request			

# HOW ALTHEN'S TECHNOLOGY ELIMINATES WEAR FOR LONGER LIFE

Althen's Inductive technology is a major advance in displacement sensor design. Our displacement transducers have the simplicity of a potentiometer with the life of an LVDT/RVDT.

Our technology combines the best in fundamental inductive principles with advanced micro-electronic integrated circuit technology. An Althen sensor, based on simple inductive coils using Althen's ASIC control technology, directly measures absolute position giving a DC analogue output signal. Because there is no contact between moving electrical components, reliability is high and wear is eliminated for an exceptionally long life.

It also overcomes the drawbacks of LVDT technology – bulky coils, poor length-to-stroke ratio and the need for special magnetic materials, no requirement for separate signal conditioning.

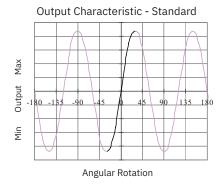
We also offer a range of ATEX-qualified intrinsically-safe sensors.

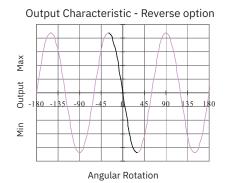
P502 .	а	b	С	d	е	f	g
1 302 .	Displacement	Output	Adjustments	Connections	Option	Option	Z-code

a Displacement			
Factory set to any angle from 0-5° (±2.5°) to 0-15° (±7.5°) (e.g. 0-8°)			
b Output			
Supply V <sub>dc</sub> (tolerance)	Output	Code	
+5V (4.5 - 5.5V)	0.5 - 4.5V (ratiometric with supply)	А	
±15V nom. (±9 - 28V)	±5V	В	
+24V nom. (13 - 28V)	0.5 - 9.5V	С	
±15V nom. (±13.5 - 28V)	±10V	D	
+24V nom. (18 - 28V)	4 - 20mA (2 wire)	E	
+24V nom. (13 - 28V)	4 - 20mA (3 wire Sink)	F	
+24V nom. (9 - 28V)	0.5 - 4.5V	G	
+24V nom. (13 - 28V)	4 - 20mA (3 wire Source)	Н	
Supply Current: 'A' 10mA nominal, 12mA max. 'B', 'D' & 'G' 12mA nominal, 15mA max. 'E' 26mA max. 'F' & 'H' 32mA nominal, 35mA max.			
c Calibration Adjustments		Code	
Accessible default †			
Sealed			

d Connections	Code		
Connector IP65 4 pin (3+earth) DIN 43650 'C'			
Connector IP65 4 pin (3+earth) DIN 43650 'C' pre-wired			
Cable gland IP67 M12, nylon			
Cable gland, short† IP67, metal	Mxx		
Specify required cable length 'xx' in cm. e.g. L2000 specifies axial cable gland with 20 m of cable, 50 cm supplied as standard.  †Nb: restricted cable pull strength.			
e Shaft Option	Code		
None default			
Sprung to stop up to 100° maximum			
f Sensor Mounting			
Flange default			
Servo Mount			
See drawing P502-11 for details.			
g Z-code (optional)	Code		
Connector IP67 M12 IEC 61076-2-101 must have options 'Y' & 'J'			
Connector IP67 M12 IEC 61076-2-101 must have option 'J'			





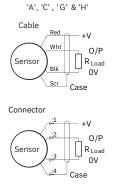


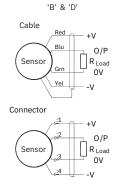
# INSTALLATION INFORMATION

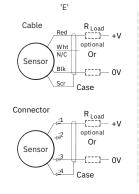
Output Option	Output Description	Supply Voltage: V <sub>s</sub> (tolerance)	Load resistance: (include leads for 4 to 20mA O/Ps)
А	0.5 - 4.5V (ratiometric with supply)	+5V (4.5 - 5.5V)	≥ 5kΩ
В	±5V	±15V nom. (±9 - 28V)	≥ 5kΩ
С	0.5 - 9.5V	+24V nom. (13 - 28V)	≥ 5kΩ
D	±10V	±15V nom. (±13.5 - 28V)	≥ 5kΩ
Е	4 - 20mA (2 wire Current Loop)	+24V nom. (18 - 28V)	≈ 0 - 300 $\Omega$ max. @24V ~ 1.2 to 6V across 300 $\Omega$ {RL max. = (V <sub>s</sub> - 18) / 20 <sup>-3</sup> }
F	4 - 20mA (3 wire Sink)	+24V nom. (13 - 28V)	≈ 0 - 950 $\Omega$ max. @24V ~ 3.8 to 19V across 950 $\Omega$ {RL max. = (V <sub>s</sub> - 5) / 20 <sup>-3</sup> }
G	0.5 - 4.5V	+24V nom. (9 - 28V)	≥ 5kΩ
Н	4 - 20mA (3 wire Source)	+24V nom. (13 - 28V)	≈ 0 - 300 $\Omega$ max. ~ 1.2 to 6V across 300 $\Omega$

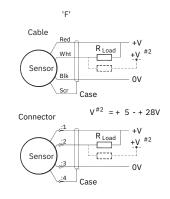
Not all output options available - see product datasheet for full options list











# GAIN AND OFFSET ADJUSTMENT

(Where accessible - Typically ± 10% Min available)

To adjust the gain or offset use a small potentiometer adjuster or screwdriver 2mm across. Do not apply too much force on the potentiometers.





#### MECHANICAL MOUNTING

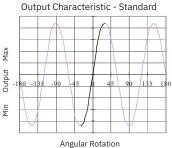
Flange mounted or servo mount, with appropriate clips - see drawing P502-11. The sensor should be mounted with minimal axial and radial loading on the shaft for optimum life. It is recommended that the shaft is coupled to the drive using a flexible coupling. Tests indicate that life in excess of 16 million cycles can be achieved with 1kg side and end load.

#### INCORRECT CONNECTION PROTECTION LEVELS

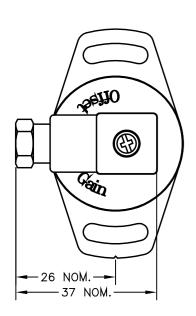
А	Not protected – the sensor is not protected against either reverse polarity or over-voltage. The risk of damage should be minimal where the supply current is limited to less than 50mA.
B & D	Supply leads diode protected. Output must not be taken outside ± 12V.
C & G	Supply leads diode protected. Output must not be taken outside 0 to 12V.
E, F & H	Protected against any misconnection within the rated voltage.

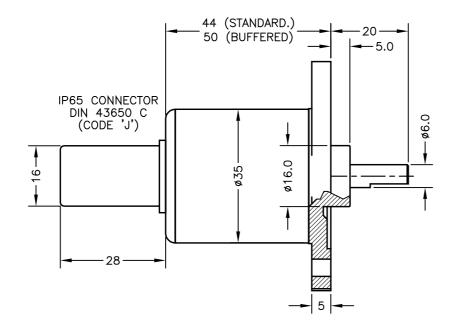
### OUTPUT CHARACTERISTIC

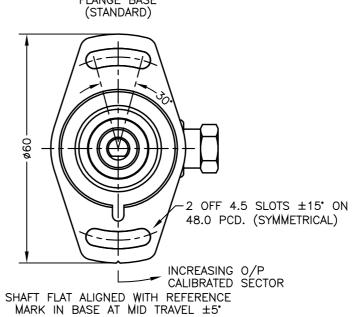
The sensor has full rotational freedom and six sectors, 60° apart, over which linear response can be achieved. At the mid point of the calibrated range the output signal will be half full scale deflection, and the flat on the shaft is aligned with the registration mark in the base of the sensor. In the calibrated range the output increases as the shaft is rotated in an anticlockwise direction viewed from the shaft. The calibrated output is factory set to be between 5 and 15°.

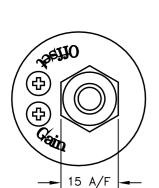


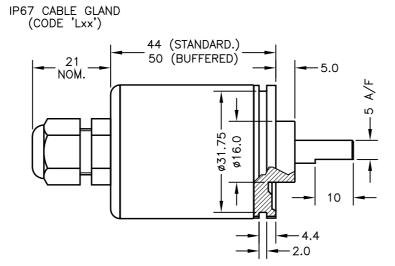
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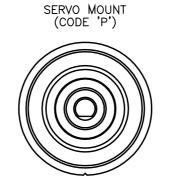




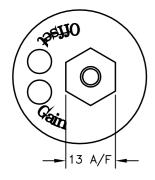


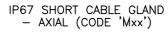


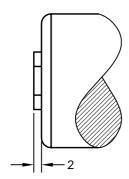




GAIN AND OFFSET ADJUSTMENTS SEALED (CODE 'Y')







D	ELEC. OPTIONS AMENDED.	PDM
Ε	FLANGE TH'KNESS ADDED.	PDM
F	ADDITIONAL DIMS/VIEWS ADDED.	PDM
G	DISP. 5 TO 15° WAS 5 TO 20° RAN442	PDM
Н	RANGE NOTE AMENDED ~ RAN1200	PDM

CE

DRAWINGS NOT TO BE CHANGED WITHOUT REFERENCE TO THE CHANGE PROCEDURE. CHANGES TO PARTS USED IN INTRINSICALLY SAFE PRODUCT MUST BE APPROVED BY THE AUTHORISED PERSON THIS IS AN UNCONTROLLED PRINT AND WILL NOT BE UPDATED.

CHECKED BY X ±0.4 X.X ±0.2 RDS X.XX ±0.1 DIMS mm D 18/10/06 E 05/01/10 F 06/07/11 G 07/11/13 P502 RIPS SMALL ANGLE ROTARY SENSOR H 11/09/17 SCALE 10mm DRAWING P502-11 REV H SHEET 1 OF 1

	ELECTRICAL OF HOUSE SI ECH TORTHOUS
	<u>OUTPUT</u> <u>SUPPLY</u>
	A 0.5 TO 4.5V RATIOMETRIC 5V STANDARD
FLANGE BASE	N   B   ±5V
(STANDARD)	E   C   0.5 TO 9.5V 24V
	D
	SUPPLY CURRENT 12mA TYP. 20mA MAX. BUFFERED
(G-+-D)	E 4 TO 20mA 2-WIRE 24V
	SUPPLY CURRENT 12mA TYP. 20mA MAX. BUFFERED  E 4 TO 20mA 2-WIRE 24V  F 4 TO 20mA 3-WIRE SINK 24V
	H 4 TO 20mA 3-WIRE SOURCE 24V
1	SINK VERSION OUTPUT COMPLIANCE 5-28V
	SOURCE VERSION DRIVE 300Ω MAX TO OV
	CABLE: 0.2mm², O/A SCREEN, PUR JACKET - SUPPLIED
	WITH 50cm OR REQUIRED LENGTH IN cm. e.g. 'L50'
	3-CORE: JACKET Ø4mm
	4-CORE: JACKET Ø4.6mm
	CABLE/CONNECTOR* CONNECTIONS; 3 CORE 4 CORE CONNECTOR
2 OFF 4 5 CLOTS +15' ON	RED RED :1 +Ve
-2 OFF 4.5 SLOTS ±15' ON 48.0 PCD. (SYMMETRICAL)	BLACK GREEN :3 OV
40.0 PCD. (STMMETRICAL)	YELLOW :4 -Ve - OPTIONS: B OR D
トビナ・ゴ	WHITE BLUE :2 OUTPUT
	SCREEN SCREEN :4 BODY - OPTIONS: A, C, E-H
INCREASING O/P	*CONNECTORS; MAXIMUM CONDUCTOR CROSS SECTION 0.75mm²
CALIBRATED SECTOR	RANGE OF DISPLACEMENT FROM 0-5° TO 0-15° e.g.12°,
FLAT ALIGNED WITH REFERENCE	IN INCREMENTS OF 1°.
IN BASE AT MID TRAVEL ±5°	BODY MATERIAL:- STAINLESS STEEL.
	FLANGE BASE MATERIAL:— ALUMINIUM.
	SERVO MOUNT MATERIAL:— ALUMINIUM.

FURTHER OPTIONS:

**ELECTRICAL OPTIONS/ SPECIFICATIONS** 

SPRING RETURN (CODE 'N') AVAILABLE UP TO ±50° CALIBRATED OUTPUT, PHYSICAL STOPS ±55° NOTE STANDARD DEVICE HAS NO STOPS.