



α RM36

System Features

- Excellent immunity to IP68
- Non-contact, frictionless design
- High speed operation to 30,000 rpm
- 36 mm diameter body
- Accuracy $\pm 0.5^\circ$
- Simple installation
- Low inertia
- Stainless steel body option
- CE compliant, including RoHS
- see Declaration of conformity



Description

The RM36 is a high-speed magnetic rotary encoder designed for use in harsh industrial environments. The non-contact two-part design removes the need for seals or bearings ensuring long-term reliability and simple installation.

The encoder comprises a magnetic actuator and a separate encoder body. Rotation of the magnetic actuator is sensed by a custom encoder chip within the body, and processed to the required output. The encoder chip processes the signals received to provide resolutions to 13 bit (8,192 positions per revolution) with high operational speeds. Resolution options include binary and decimal. Output signals are provided in industry standard absolute, incremental or linear formats.

The compact encoder body is 36mm in diameter and provides dirt immunity to IP68. The RM36 can be used in a wide range of applications, including marine, medical, print, converting, industrial automation, metal working, motor control and instrumentation.

Product Range

5V power supply version

- RM36 I - incremental with 80 to 2,048 pulses per revolution (320 to 8,192 counts per revolution with x 4 evaluation).
- RM36 S - synchro serial interface (SSI) with 320 to 8,192 positions per revolution.

24V power supply version

- RM36 I - incremental with 80 to 2,048 pulses per revolution (320 to 8,192 counts per revolution with x 4 evaluation).
- RM36 V - linear voltage output in a range of variants
- RM36 C - linear current output in a range of variants

Electrical & Operating Specifications

Humidity (for IP64 version)	Storage 95% maximum relative humidity (non-condensing) (IEC 61010-1) Operating 80% maximum relative humidity (non-condensing) (IEC 61010-1)
Acceleration	Operating 500 m/s ² EN 60068-2-7: 1993 (IEC 68-2-7:1983)
Shock (non-operating)	1000 m/s ² , 6 ms, 1/2 sine EN 60068-2-7: 1993 (IEC 68-2-27:1987)
Vibration operating	100 m/s ² max at 55 to 2000 Hz EN 60068-2-6: 1996 (IEC 68-2-6:1995)
EMC compliance	EN 61326
Cable	Outside diameter 5 mm
Mass	Encoder unit 1 m cable (no connector) 85g. Stainless steel variant 160 g. Magnetic actuator 12 g
Environmental sealing	IP64 (IP68 optional) EN 60529

07/2021 | version 0001

SUPPLY VOLTAGE 5 Vdc

RM36 IC - Incremental, RS422, 5 V

Square wave differential line driver to RS422

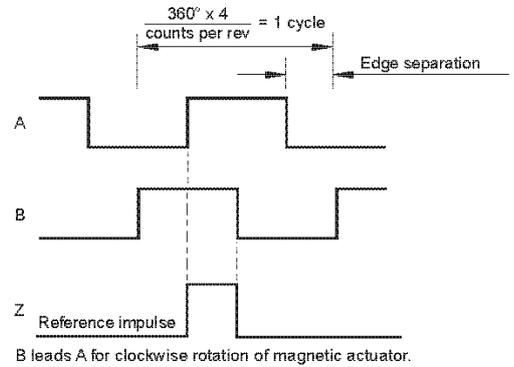
Power Supply	$V_{dd} = 5 V \pm 5 \%$
Power Consumption	35 mA
Output Signals	A, B, Z, A-, B-, Z- (RS422)
Maximum Cable Length	50 m
Connector Options	9 pin 'D' type plug (standard)
Temperature	Operating: -40°C to +125°C (IP64)
	Storage: -40°C to +85°C

Resolution Options (counts per revolution)	Maximum Speed (rpm)	Accuracy*	Hysteresis
128, 256	60,000	$\pm 0.7^\circ$	0.45°
320, 400, 500, 512	30,000	$\pm 0.7^\circ$	0.18°
800, 1,000, 1,024	20,000	$\pm 0.5^\circ$	0.18°
1,600, 2,000, 2,048	10,000	$\pm 0.5^\circ$	0.18°
4,096	5,000	$\pm 0.5^\circ$	0.18°
8,192	2,500	$\pm 0.5^\circ$	0.18°

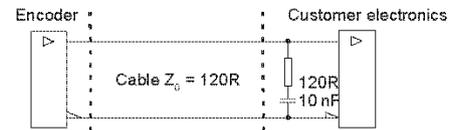
* Worst case within operational parameters including magnet position and temperature.

Timing Diagram

Complementary signals not shown



Recommended signal termination



RM36 SC - Absolute binary synchro-serial interface (SSI)

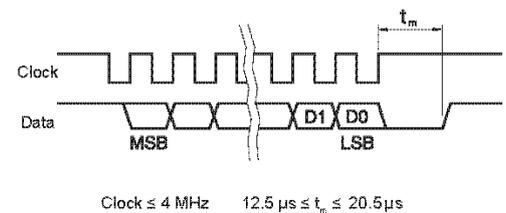
Serial encoded absolute position measurement

Power Supply	$V_{dd} = 5 V \pm 5 \%$
Power Consumption	35 mA
SSI Output Code	Natural Binary
Data Output	Serial Data (RS422)
Data Input	Clock (RS422)
Repeatability	$\leq 0.07^\circ$
Maximum Cable Length	100 m (at 1 MHz)
Connector Options	9 pin 'D' type plug (standard) Flying lead
Temperature	Operating: -40°C to +125°C (IP64)
	Storage: -40°C to +85°C

Resolution Options (counts per revolution)	Maximum Speed (rpm)	Accuracy*	Hysteresis
128, 256	60,000	$\pm 0.7^\circ$	0.45°
320, 400, 500, 512	30,000	$\pm 0.7^\circ$	0.18°
800, 1,000, 1,024	20,000	$\pm 0.5^\circ$	0.18°
1,600, 2,000, 2,048	10,000	$\pm 0.5^\circ$	0.18°
4,096	5,000	$\pm 0.5^\circ$	0.18°
8,192	2,500	$\pm 0.5^\circ$	0.18°

* Worst case within operational parameters including magnet position and temperature.

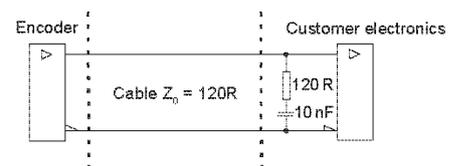
Timing Diagram



Position increases for clockwise rotation of magnetic actuator.

Recommended signal termination

For data output lines only



RM36 SI - Absolute binary synchro-serial (SSI) + Incremental, RS422, 5 V

Complex feedback device for absolute position at start up as well as during operation + incremental outputs. Both the incremental and the SSI output always have the same fixed resolution.

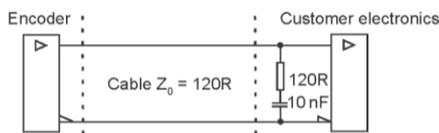
Power Supply	$V_{dd} = 5 V \pm 5 \%$
Power Consumption	35 mA
SSI Output Code	Natural Binary
Data Output	Serial Data (RS422)
Data Input	Clock (RS422)
Incremental Outputs	A, B, Z, A-, B-, Z- (RS422)
Connector Options	15 pin 'D' type plug (standard) Flying Lead
Maximum Cable Length	50 m
Temperature	Operating: $-40^{\circ}C$ to $+125^{\circ}C$ (IP64) $-40^{\circ}C$ to $+85^{\circ}C$ (IP68) Storage: $-40^{\circ}C$ to $+85^{\circ}C$

Resolution Options (counts per revolution)	Maximum Speed (rpm)	Accuracy*	Hysteresis
128, 256	60,000	$\pm 0.7^{\circ}$	0.45°
320, 400, 500, 512	30,000	$\pm 0.7^{\circ}$	0.18°
800, 1,000, 1,024	20,000	$\pm 0.5^{\circ}$	0.18°
1,600, 2,000, 2,048	10,000	$\pm 0.5^{\circ}$	0.18°
4,096	5,000	$\pm 0.5^{\circ}$	0.18°
8,192	2,500	$\pm 0.5^{\circ}$	0.18°

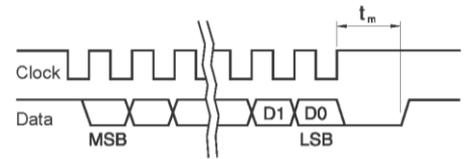
* Worst case within operational parameters including magnet position and temperature.

Recommended signal termination

For incremental signals + SSI data output lines only

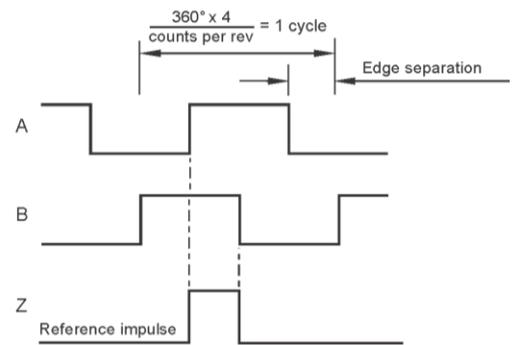


Timing Diagram - SSI



Clock ≤ 4 MHz $12.5 \mu s \leq t_m \leq 20.5 \mu s$
Position increases for clockwise rotation of magnetic actuator.

Timing diagram - Incremental
Complementary signals not shown



B leads A for clockwise rotation of magnetic actuator.

SUPPLY VOLTAGE 24 Vdc

RM36 IA - Incremental, push-pull, 24 V

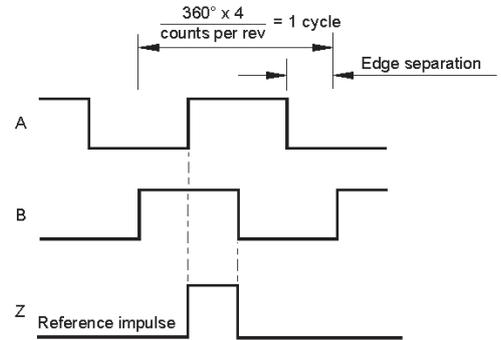
Power Supply	$V_{dd} = 8\text{ V to }26\text{ V}$
Power Consumption	50 mA
Maximum Output Load	30 mA
Output Signals	A, B, Z, A-, B-, Z- (RS422)
Resolution	80 to 2,048 pulses per revolution (320, 400, 500, 512, 800, 1,000, 1,024, 1,600, 2,000, 2,048, 4,096, 8,192 counts per revolution)
Maximum Cable Length	20 m
Connector Options	9 pin 'D' type plug (standard) Flying Lead
Temperature	Operating: $-40^{\circ}\text{C to }+125^{\circ}\text{C}$ (IP64) $-40^{\circ}\text{C to }+85^{\circ}\text{C}$ (IP68) Storage: $-40^{\circ}\text{C to }+85^{\circ}\text{C}$

Resolution Options (counts per revolution)	Maximum Speed (rpm)	Accuracy*	Hysteresis
320, 400, 500	30,000	$\pm 0.7^{\circ}$	0.18°
512	30,000	$\pm 0.7^{\circ}$	0.45°
800, 1,000, 1,024	20,000	$\pm 0.5^{\circ}$	0.18°
1,600, 2,000, 2,048	10,000	$\pm 0.5^{\circ}$	0.18°
4,096	5,000	$\pm 0.5^{\circ}$	0.18°
8,192	2,500	$\pm 0.5^{\circ}$	0.18°

* Worst case within operational parameters including magnet position and temperature.

Timing Diagram

Complementary signals not shown



B leads A for clockwise rotation of magnetic actuator.

RM36 IB - Incremental, open collector NPN, 24 V

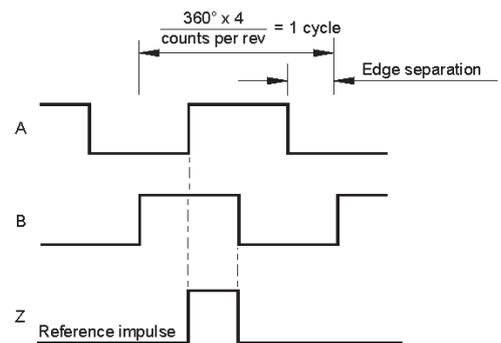
Square wave output

Power Supply	$V_{dd} = 8\text{ V to }26\text{ V}$
Power Consumption	50 mA
Maximum Output Load	20 mA
Output Signals	A, B, Z
Maximum Cable Length	20 m
Connector Options	9 pin 'D' type plug (standard) Flying lead
Temperature	Operating: $-40^{\circ}\text{C to }+125^{\circ}\text{C}$ (IP64) $-40^{\circ}\text{C to }+85^{\circ}\text{C}$ (IP68) Storage: $-40^{\circ}\text{C to }+85^{\circ}\text{C}$

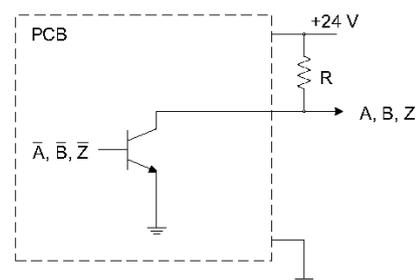
Resolution Options (counts per revolution)	Maximum Speed (rpm)	Accuracy*	Hysteresis
320, 400, 500	30,000	$\pm 0.7^{\circ}$	0.18°
512	30,000	$\pm 0.7^{\circ}$	0.45°
800, 1,000, 1,024	20,000	$\pm 0.5^{\circ}$	0.18°
1,600, 2,000, 2,048	10,000	$\pm 0.5^{\circ}$	0.18°
4,096	5,000	$\pm 0.5^{\circ}$	0.18°
8,192	2,500	$\pm 0.5^{\circ}$	0.18°

* Worst case within operational parameters including magnet position and temperature.

Timing Diagram



Recommended signal termination



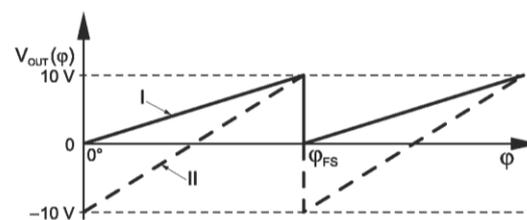
RM36 Vx - Linear Voltage Output

Power Supply	Type I: +20 V to +30 V DC Type II: ±12 V to ±16 V DC
Power Consumption	40 mA typical
Output Voltage	Type I: 0 V to 10 V DC Type II: -10 V to +10 V DC
Output Loading	Max. 10 mA
Nonlinearity	1 %
Maximum Cable Length	20 m
Connector Options	9 pin 'D' type plug (standard) Flying Lead
Temperature	Operating: -25°C to +70°C Storage: -40°C to +85°C
Maximum Speed	30,000 rpm

Output type and Electrical variant

Φ_{FS}	Type I				Type II			
	360°	180°	90°	45°	360°	180°	90°	45°
CW	VA	VB	VC	VD	VM	VN	VP	VQ
CCW	VE	VF	VG	VH	VR	VS	VT	VV

Electrical output/shaft position



RM36 Cx - Linear Current Output

Power Supply	$V_{dd} = +20 \text{ V to } +30 \text{ V DC}$
Power Consumption	50 mA plus output current
Output Current	4 mA to 20 mA
Output Loading	$R_L = 0 \text{ to } \frac{V_{dd}}{I_{OUTmax}}$
Nonlinearity	1 %
Maximum Cable Length	20 m
Connector Options	9 pin 'D' type plug (standard) Flying Lead
Temperature	Operating: -25°C to +70°C Storage: -40°C to +85°C
Maximum Speed	30,000 rpm

Output type and Electrical variant

Φ_{FS}	360°	180°	90°	45°
CW	CA	CB	CC	CD
CCW	CE	CF	CG	CH

Electrical output/shaft position

