





S115

Rugged Submersible Stand-Alone Linear Position Sensor

Position feedback for industrial and scientific applications

FEATURES

- Non-contacting inductive technology to eliminate wear
- Travel set to customer's requirement
- Compact and self-contained
- High durability and reliability
- High accuracy and stability
- Sealing to IP68 10Bar

Our S115 is a heavy-duty version of the S114 sensor with a stronger 12.6mm push rod, recommended for applications where vibration is an issue or there is a need for longer travel sensors which are to be mounted horizontally between rod eyes.

It remains an affordable, durable, highaccuracy position sensor designed for applications where the sensor would be completely submerged during normal operation.

The unit is highly compact and space-efficient, being responsive along almost its entire length. Like all sensors, the S115 provides a linear output proportional to travel.

Each sensor is supplied with the output calibrated to the travel required by the customer, any stroke from 0-5mm to 0-800mm and with full EMC protection built in. The sensor is very robust, the body and push rod being made of 316 stainless steel for long service life and environmental resistance. Overall performance, repeatability and stability are outstanding over a wide temperature range. The sensor is easy to install with mounting options including stainless steel M8 rod eye bearings and body clamps. The push rod can be supplied free or captive, with female M8 thread, an M8 rod eye, or dome end. Captive push rods can be sprung loaded, in either direction, on sensors up to 300mm of travel.

The S115 also offers a selection of mechanical and electrical options, environmental sealing is to IP68 10 Bar.







SPECIFICATION

Dimensions

Body diameter 35 mm

Body length (Axial version) calibrated travel + 168 mm Body length (Radial version) calibrated travel + 189 mm

Push rod extension calibrated travel + 7 mm, OD 12.6 mm

For full mechanical details see drawing S115 -11

Independent Linearity $\leq \pm 0.25\%$ FSO @ 20°C - up to 450 mm $\leq \pm 0.5\%$ FSO @ 20°C - over 450 mm

 \leq ± 0.5% FSO @ 20°C - over 450 mm \leq ± 0.1% FSO @ 20°C* available upon request.

*Sensors with calibrated travel from 10 mm up to 400 mm.

Temperature Coefficients $< \pm 0.01\%$ /°C Gain & $< \pm 0.01\%$ FS/°C Offset

Frequency Response > 10 kHz (-3dB)

> 10 kHz (-3dB) > 300 Hz (-3dB) 2 wire 4 to 20 mA

Resolution Infinite

Noise < 0.02% FSO

Environmental Temperature Limits (Non Icing)

Sealing IP68 10 Bar

EMC Performance EN 610 00-6-2, EN 610 00-6-3

 Vibration
 IEC 68-2-6:
 10 g

 Shock
 IEC 68-2-29:
 40 g

 MTBF
 350,000 hrs 40°C Gf

Drawing List

S115-11 Sensor Outline

Drawings, in AutoCAD® dwg or dxf format, available on request.

Version | 11.2022

Do you need a position sensor made to order to suit a particular installation requirement or specification? We'll be happy to modify any of our designs to suit your needs - please contact us with your requirements.





PIPS®-based displacement transducers have the simplicity of a potentiometer with the life of an LVDT/RVDT.

PIPS® technology combines the best in fundamental inductive principles with advanced micro-electronic integrated circuit technology. A PIPS® sensor, based on simple inductive coils using 's ASIC control technology, directly measures absolute position giving a DC analogue output signal. Because there is no contact between moving electrical components, reliability is high and wear is eliminated for an exceptionally long life.

PIPS® overcomes the drawbacks of LVDT technology — bulky coils, poor length-to-stroke ratio and the need for special magnetic materials. It requires no separate signal conditioning.

Our LIPS® range are linear sensors, while RIPS® are rotary units and TIPS® are for detecting tilt position. Ask us for a full technical explanation of PIPS® technology.

We also offer a range of ATEX-qualified intrinsicallysafe sensors.

TABLE OF OPTIONS

CALIBRATED TRAVEL: Factory set to any length from 0-5mm to 0-800mm (e.g. 254mm)

ELECTRICAL IN TERFACE OPTIONS

0 U	TPUT SIGNAL	SUPPLY INPUT	OUTPUT LOAD
	andard: 5-4.5 V dc ratiometric	+5 V dc nom. ± 0.5V.	5k Ω min.
0. ±! 0.	uffered: 5-4.5 V dc 5V dc 5-9.5 V dc 10 V dc	+ 24V dc nom. + 9-28V. ±15V dc nom. ± 9-28V. + 24V dc nom. + 13-28V. ±15 V dc nom. ± 13.5-28V.	$5k\Omega$ min. $5k\Omega$ min. $5k\Omega$ min. $5k\Omega$ min.
Sι	ipply Current	10 mA typical, 20mA maximum.	
4-	20mA (2 wire) (3 wire sink) (3 wire source)	+ 24 V dc nom. + 18-2 8V. + 24 V dc nom. + 13-2 8V. + 24 V dc nom. + 13-2 8V.	300 Ω @ 24V. 950 Ω @ 24V. 300 Ω max.

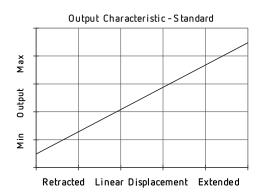
CONNECTOR/CABLE OPTIONS

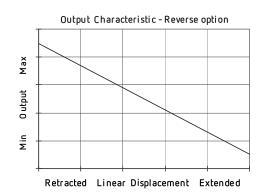
Cable with Pg 7 gland Axial or Radial, IP68 10 Bar Cable length >5 0 cm — please specify length in cm

MOUNTING OPTIONS

M8 rod eye bearing (radial versions), Body Tube Clamp/s (axial or radial versions).

PUSH ROD OPTIO NS – standard retained with M8x1.25 female thread, M8 rod eye bearing, Dome end, Sprung loaded (retraction or extension) or Free.









INTRINSICALLY SAFE - GAS/VAPOUR ATMOSPHERES

а	b	С	d	е	f	9	h
S115 . Displacemen	: Ou tput	Connections	Option	Option	Option	0 ption	Z-code

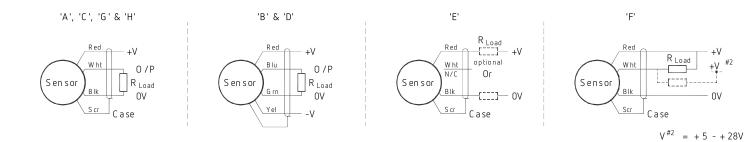
a Displacement (mm)		Value
Displacement in mm	e.g. 0 - 254 mm	254
b Output		
Supply V dc V_s (tolerance)	Output	Code
+5V (4.5 - 5.5V)	0.5 – $4.5V$ (ratiometric with supply)	Α
±15V nom. (±9 - 28V)	± 5V	В
+ 24V nom. (13 - 28V)	0.5 - 9.5V	С
± 15V nom. (±13.5 - 28V)	±10V	D
+ 24V nom. (18 - 28V)	4 - 20mA 2 wire	Е
+ 24V nom. (13 - 28V)	4 - 20mA 3 wire Sink	F
+ 24V nom. (9 - 28V)	0.5 - 4.5V	G
+ 24V nom. (13 - 28V)	4 - 20mA 3 wire Source	Н
c Connections Cable or	Connector	Code
Cable Gland - Radial	IP67 Pg7	l xx
Cable Gland - Axial	IP67 Pg7	Lxx
	specify required cable length specified in cm. e. es of cable. Nb: restricted cable pull strength.	g. L2000
d Body Fittings		Code
None - default		blank
M8 Rod-eye Bearing	Radial body style only	N
Body Clamps - 1 pair		Р
Body Clamps - 2 pairs		P2
e Sprung Push Rod		Code
None - default		blank
Spring Extend	Up to 300mm displacement.	R
Spring Retract	Captive push rod only.	S
f Push Rod Fittings		Code
None - default	Female Thread M8x1. 25x12 deep	blank
Dome end	Required for option 'R'	Т
M8 Rod-eye Bearing		U
g Push Rod Options		Code
Captive - default	Push rod is retained	blank
Non-captive	Push rod can depart body	٧
h Z-code		Code
≤± 0.1% @20°C Indeper	ndent Linearity displacement between	Z650





INSTALLATION INFORMATION

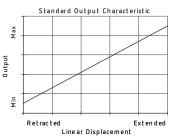
Output Option	Output Description:	Supply Voltage: V _s (tolerance)	Load resistance: (include leads for 4 to 20mA O /Ps)
Α	0.5 - 4.5V (ratiometric with supply)	+ 5V (4.5 - 5.5V)	≥ 5kΩ
В	± 5V	±15V nom. (±9 - 28V)	≥ 5kΩ
С	0.5 - 9.5V	+24V nom. (13 - 28V)	≥ 5kΩ
D	±10V	±15V nom. (±1 3.5 - 28V)	≥ 5kΩ
E	4 - 20mA 2 wire Current Loop	+ 24V nom. (18 - 28V)	≈ 0 – 300Ω max. @ 24V \sim 1.2 to 6V across 3000 $\{R_L$ max. = (V $_s$ – 18) $/$ 20 $^{-3}\}$
F	4 - 20mA 3 wire Sink	+ 24V nom. (13 - 28V)	≈ 0 - 950 Ω max. @ 24V \sim 3.8 to 19V across 950 Ω {R _L max. = (V _s - 5) / 20 ⁻³ }
G	0.5 - 4.5V	+ 24V nom. (9 - 28V)	≥ 5kΩ
Н	4 - 20mA 3 wire Source	+ 24V nom. (13 - 28V)	≈ 0 - 300Ω max. ~ 1.2 to 6V across 300Ω



Mechanical Mounting: Depending on options; Body can be mounted by M8 rod eye or by clamping the sensor body - body clamps are available, if not already ordered. Target by M8x1.25 female thread or M8 rod eye. It is assumed that the sensor and target mounting points share a common earth.

Where the free end of the cable is to be terminated in a submerged position, adequate sealing must be provided to protect connections.

Output Characteristic: Target is extended 7 mm from end of body at start of normal travel. The output increases as the target extends from the sensor body, the calibrated stroke is between 5 and 800 mm.



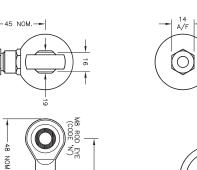
Incorrect Connection Protection levels:

- A Not protected the sensor is **not** protected against either reverse polarity or over-voltage.

 The risk of damage should be minimal where the supply current is limited to less than 50mA.
- **B & D** Supply leads diode protected. Output must not be taken outside ± 12V.
- **C & G** Supply leads diode protected. Output must not be taken outside 0 to 12V.
- **E, F & H** Protected against any misconnection within the rated voltage.







IP68 CABLE GLAND (CODE

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FORCE (N)

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WITH OPTIONS 'R' OR

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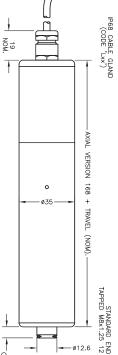
SPRING FORCE V STROKE (CODE 'R' OR 'S')

50 STROKE (mm) 100 200

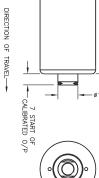
250 300

5 NOM.





DIRECTION OF TRAVEL-



DEEP



SPRING RETURN PUSH-ROD, TRAVEL <300mm RETURN TO EXTENDED POSITION (CODE R) RETURN TO RETRACTED POSITION (CODE S)

PUSH-ROD FREE (CODE 'V') - NOT AVAILABLE WITH SPRUNG OPTIONS.

VERSION 268 +

189 + TRAVEL TRAVEL

· (NOM) (NOM).

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RANGE OF DISPLACEMENT FROM 0-5mm TO 0-800mm e.g.76, IN INCREMENTS OF 1mm.

BODY MATERIAL: STAINLESS STEEL 316. FURTHER OPTIONS: SINGLE PAIR OF BODY CLAMPS 'P'
TWO PAIRS OF BODY CLAMPS 'P2'





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2	JSED IN INTRINSICALLY SAFE PRODUCT MUST BE APPROVED	CHANGED WITHOUT REFERENCE TO THE CHANGE PROCEDURE.		

FIRST ISSUE ~ RAN1044

RANGE WAS 50-600mm RAN1056

OPTION 'S' ADDED ~ RAN1108 GE NOTE AMENDED ~ RAN120

MAXIMUM WORKING DEPTH: 100 METRES/328 FEET. WHERE THE FREE END OF THE CABLE IS TO BE TERMINATED IN A SUBMERGED POSTION, ADEQUATE SEALING MUST BE PROVIDED TO PROTECT CONNECTIONS.

THE PUSH-ROD RETRACTS A FURTHER 4mm NOM. FROM START OF CALIBRATED TRAVEL. STANDARD VERSIONS THE PUSH-ROD EXTENDS A FURTHER 8mm NOM. FROM END OF CALIBRATED TRAVEL, FOR SPRUNG VERSIONS. 'R': 1mm, 'S': 2mm. 'Y CODED PUSH-ROD WILL DEPART SENSOR BODY.

SHEET 1 OF 1	南	ş			1	
RE	_	S115-11		DRAWING NUMBER	CALE 12.5mm	SCALE
	7	POSITION SENSOR	9	700		
Ź	ıΨ	STAND-ALONE LINEAR	2 2	STAN		
ERSI	ΒM	S115 RUGGED SUBMERSIBLE	RUG	S115		
		_	ğ	DESCRIPTION	06/09/17	0
DIMS mm	L		,	4	14/09/16	0
××		RDS	4	1	09/11/15	В
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The information provided herein is to the best of our knowledge true and accurate, it is provided for guidance only. All specifications are subject to change without prior notification.

Althen stands for pioneering measurement and custom sensor solutions. In addition we offer services such as calibration, design & engineering, training and renting of measurement equipment.