ALTHEN SENSORS & CONTROLS

mm **S623**

APPLICATION

- Non-contacting inductive technology to eliminate wear
- Angle set to customer's requirement
- Compact and self-contained
- High durability and reliability
- High accuracy and stability
- Sealing to IP68 350 Bar

As a leading designer and manufacturer of linear, rotary, tilt and intrinsically safe position sensors, Althen has the expertise to supply a sensor to suit a wide variety of applications. Our S623 is an affordable, durable, high-accuracy tilt sensor designed to provide feedback for arduous underwater applications such as ROVs.

The S623, like all Althen sensors, is supplied with the output calibrated to the angle required by the customer, between 15 and 160 degrees and with full EMC protection built in. The sensor provides a linear output proportional with the rotation of the sensor. There is a machined registration mark to identify the calibrated mid point. Overall performance, repeatability and stability are outstanding over a wide temperature range. Electrical connections to the sensor are made via a wet mate connector. The sensor has a rugged 316 stainless steel body and mounting flange. The S623 offers a range of electrical options. Environmental sealing is to IP68 350 Bar.

SPECIFICATIONS

Dimensions[1]	
Body diameter	40 mm
Flange Diameter	69 mm
Body Length (to mounting face)	81 mm axial 90mm radial
Independent Linearity/Hysteresis (combined error)	≤ ± 0.25% - up to 100°
Pressure Effects	Output changes with pressure < 1°
Temperature Coefficients	< ± 0.01%/°C Gain & < ± 0.01%FS/°C Offset
Response Time	250 mS @ 20°C typ.
Resolution	Infinite
Damping Ratio	0.2 : 1 (0.6 nom. @ 25°C)
Noise	< 0.02% FSO
Environmental Temperature Limits	
Operating	-4°C to +50°C all output options
Storage	-4°C to +50°C
Sealing	IP68 350 Bar
EMC Performance	EN 61000-6-2, EN 61000-6-3
Vibration	IEC 68-2-6: 10 g
Shock	IEC 68-2-29: 40 g
MTBF	350,000 hrs 40°C Gf
Drawing List[2]	
S623-11	Sensor Outline

[1] *For full mechanical details see drawings S623-11*
[2] *3D models, step or .igs format, available on request*

06.2025 | version 0001

HOW ALTHEN'S TECHNOLOGY ELIMINATES WEAR FOR LONGER LIFE

Althen's Inductive technology is a major advance in displacement sensor design. Our displacement transducers have the simplicity of a potentiometer with the life of an LVDT/RVDT.

Our technology combines the best in fundamental inductive principles with advanced micro-electronic integrated circuit technology. An Althen sensor, based on simple inductive coils using Althen's ASIC control technology, directly measures absolute position giving a DC analogue output signal. Because there is no contact between moving electrical components, reliability is high and wear is eliminated for an exceptionally long life.

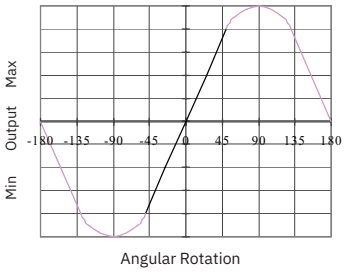
It also overcomes the drawbacks of LVDT technology – bulky coils, poor length-to-stroke ratio and the need for special magnetic materials, no requirement for separate signal conditioning.

We also offer a range of ATEX-qualified intrinsically-safe sensors.

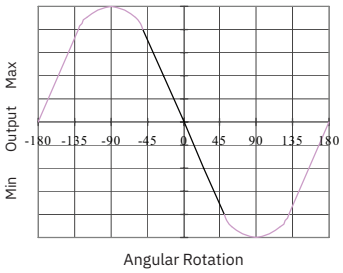
S520	.	a	b	c	d
		Displacement	Output	Connections	Z-code

a Displacement		**Value**
Factory set to any angle from 0-15° (±7.5°) to 0-160° (±80°) (e.g. 0-54°)		**54**
b Output		
Supply V_{dc} (tolerance)	**Output**	**Code**
+5V (4.5 - 5.5V)	0.5 - 4.5V (ratiometric with supply)	**A**
±15V nom. (±9 - 28V)	±5V	**B**
+24V nom. (13 - 28V)	0.5 - 9.5V	**C**
±15V nom. (±13.5 - 28V)	±10V	**D**
+24V nom. (18 - 28V)	4 - 20mA (2 wire)	**E**
+24V nom. (13 - 28V)	4 - 20mA (3 wire Sink)	**F**
+24V nom. (9 - 28V)	0.5 - 4.5V	**G**
+24V nom. (13 - 28V)	4 - 20mA (3 wire Source)	**H**
Supply Current: 'A' 10mA nominal, 12mA max. 'B', 'D' & 'G' 12mA nominal, 15mA max. 'E' 26mA max. 'F' & 'H' 32mA nominal, 35mA max.		
c Connections		**Code**
Connector axial IP68 350 Bar Wet mate 4 pin MC BH-4-M		**J50**
Connector radial IP68 350 Bar Wet mate 4 pin MC BH-4-M		**K50**
Supplied with an over-moulded MC IL-4-F connector with 0.5 m, 4-core 20 AWG (0.5mm²) EPDM cable assembly, and locking collar as standard.		
d Z-code (optional)		**Code**
≤± 0.1% FSO @20°C Independent Linearity 0 - 16° min. to 0 - 100° max.		**Z650**

Output Characteristic - Standard



Output Characteristic - Reverse option



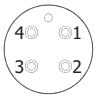
06.2025 | version 0001

INSTALLATION INFORMATION

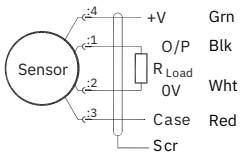
Output Option	Output Description	Supply Voltage: V_s (tolerance)	Load resistance: (include leads for 4 to 20mA O/Ps)
A	0.5 - 4.5V (ratiometric with supply)	+5V (4.5 - 5.5V)	≥ 5kΩ
B	±5V	±15V nom. (±9 - 28V)	≥ 5kΩ
C	0.5 - 9.5V	+24V nom. (13 - 28V)	≥ 5kΩ
D	±10V	±15V nom. (±13.5 - 28V)	≥ 5kΩ
E	4 - 20mA 2 wire Current Loop	+24V nom. (18 - 28V)	≈ 0 - 300Ω max. @24V ~ 1.2 to 6V across 300Ω {RL max. = $(V_s - 18) / 20^{-3}$}
F	4 - 20mA 3 wire Sink	+24V nom. (13 - 28V)	≈ 0 - 950Ω max. @24V ~ 3.8 to 19V across 950Ω {RL max. = $(V_s - 5) / 20^{-3}$}
G	0.5 - 4.5V	+24V nom. (9 - 28V)	≥ 5kΩ
H	4 - 20mA 3 wire Source	+24V nom. (13 - 28V)	≈ 0 - 300Ω max. ~ 1.2 to 6V across 300Ω

Connector Pinout Layout:

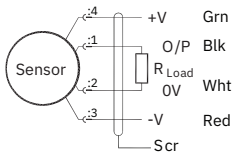
MC BH 4 M (face view)



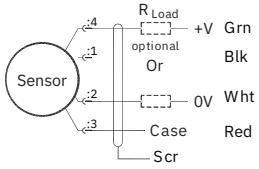
'A', 'C' , 'G' & 'H'



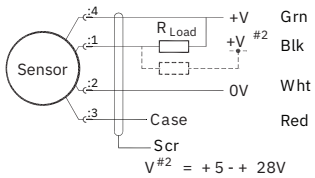
'B' & 'D'



'E'



'F'



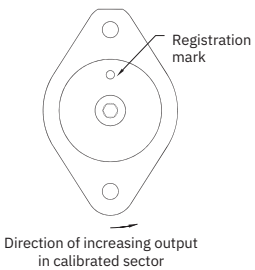
MECHANICAL MOUNTING

Flange mounted, flange holes are 5.5mm diameter on a 54mm pitch. As shipped, the sensor calibrated mid-point will be obtained with the flange in the vertical plane, as shown. Mechanical adjustment of the mid point can be achieved by loosening two M4 grub screws in the edge of the flange and rotating the sensor body. **Note:** the sensor should be mounted on a vertical face.

N.b. cable free end must be appropriately terminated to prevent water ingress into the cable.

See page 2 for connector handling instructions.

The sensor is sealed to IP68 350 Bar.



INCORRECT CONNECTION PROTECTION LEVELS

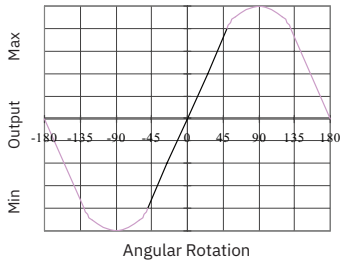
A	**Not protected** – the sensor is **not** protected against either reverse polarity or over-voltage. The risk of damage should be minimal where the supply current is limited to less than 50mA.
B & D	Supply leads diode protected. Output must not be taken outside ± 12V.
C & G	Supply leads diode protected. Output must not be taken outside 0 to 12V.
E, F & H	Protected against any misconnection within the rated voltage.

06.2025 | version 0001

OUTPUT CHARACTERISTIC

The sensor has full rotational freedom and two sectors, 180° apart, over which linear response can be achieved. At the mid point of the calibrated range the output signal will be half full scale deflection, and the flat on the shaft is aligned with the registration mark in the base of the sensor. In the calibrated range the output increases as the shaft is rotated in an anti-clockwise direction viewed from the shaft. The calibrated output is factory set to be between 15° and 160°.

Standard Output Characteristic



CONNECTOR MATING INSTRUCTIONS

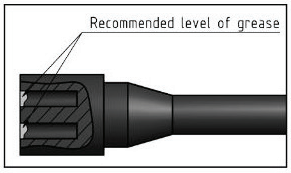
Handling

- Always apply grease mating
- Disconnect by pulling straight, not at an angle
- Do not pull on the cable and avoid sharp bends at cable entry
- When using bulkhead connector, ensure that there are no angular load
- Do not over-tighten the bulkhead nuts
- Connectors should not be exposed to extended periods of heat or direct sunlight. If a connector becomes very dry, it should be soaked in fresh water before use

Cleaning

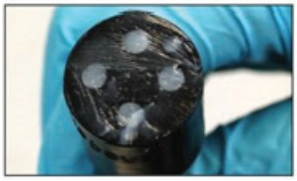
- General cleaning to remove any accumulated sand or mud on a connector should be performed using spray based contact cleaner (isopropyl alcohol)
- New grease must be applied again prior to mating

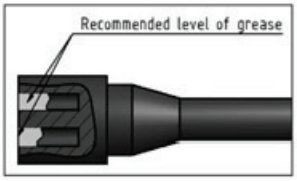
GREASING AND MATING ABOVE WATER (DRY MATE)



- Connectors must be greased with Molykote 44 Medium before every mating
- A layer of grease corresponding to approximately 1/10 of the socket depth should be applied to the female connector
- The inner edge of all the sockets should be completely covered, and a transparent layer of grease left visible on the face of the connector
- After greasing, fully mate the male and female connector in order to secure optimal distribution of grease on pins and in sockets
- To confirm that the grease has been sufficiently applied, de- mate and check for grease on every male min. Then re-mate the connector

GREASING AND MATING ABOVE WATER (WET MATE)





- Connectors must be greased with Molykote 44 Medium before every mating
- A layer of grease corresponding to approximately 1/3 of the socket depth should be applied to the female connector
- All sockets should be completely sealed, and a transparent layer of grease left visible on the face of the connector
- After greasing, fully mate the male and female connector and remove any excess grease from the connector joint

06.2025 | version 0001

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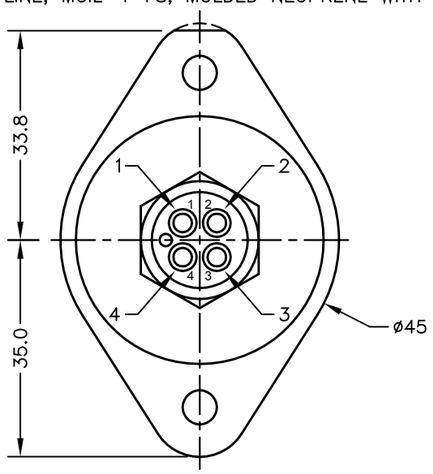
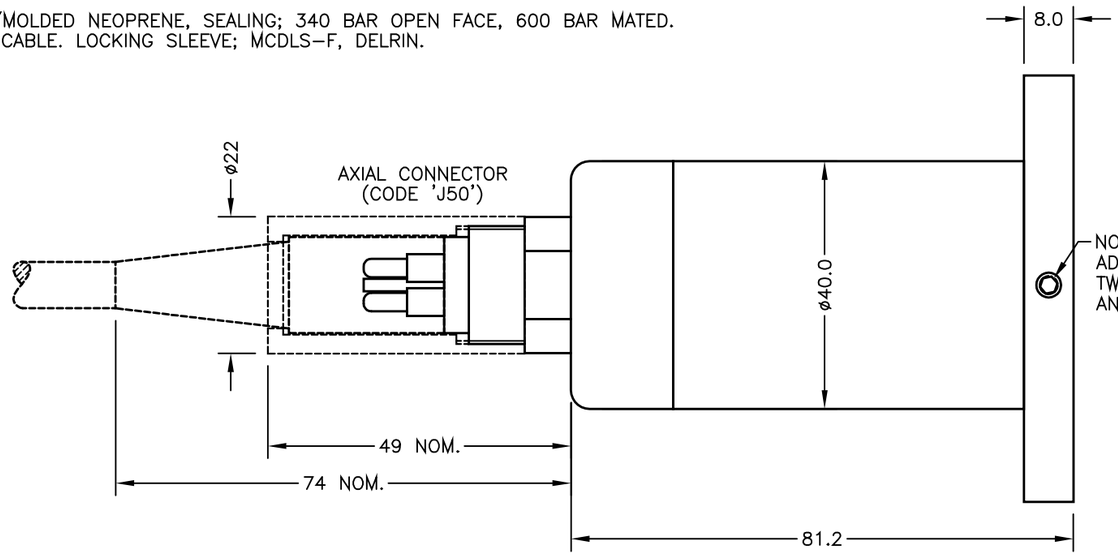
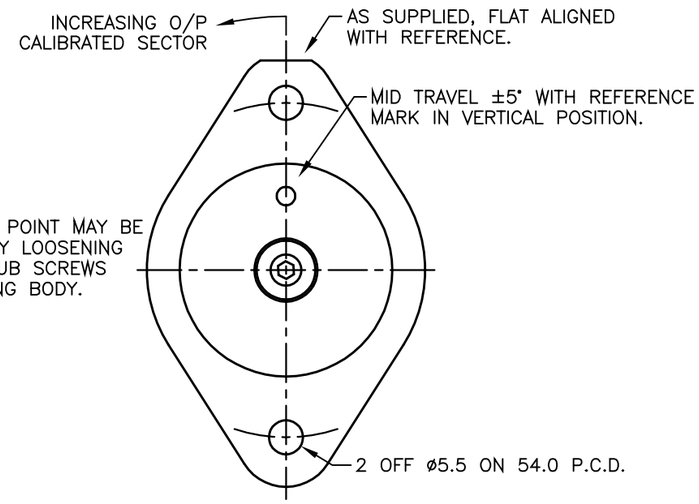
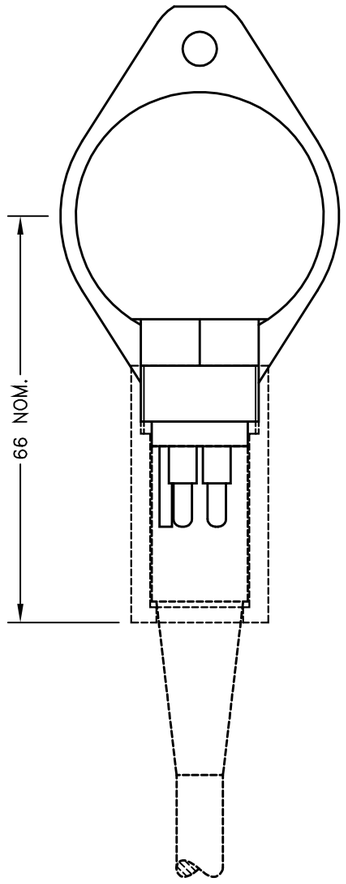
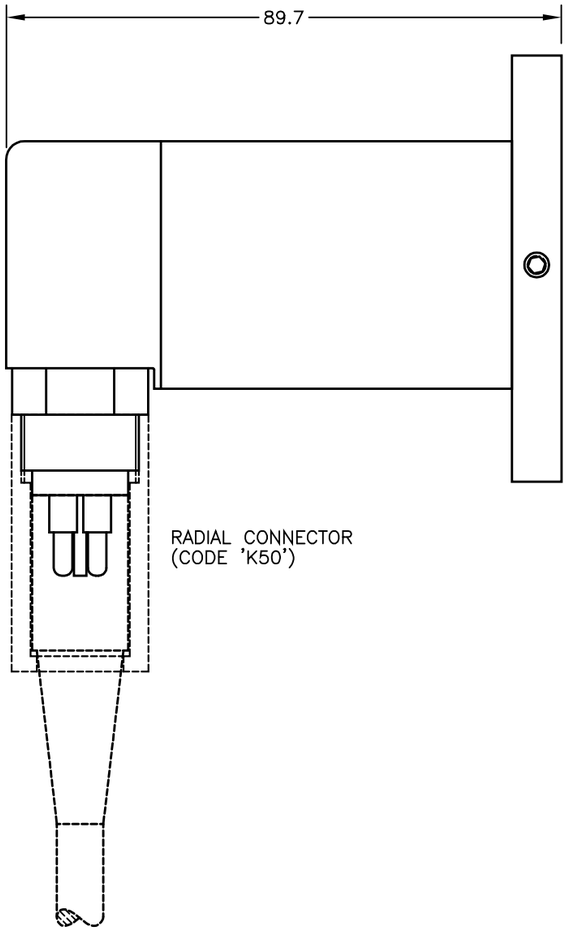
CONNECTORS; MICRO MINI WETMATE, 4–POLE.
BULKHEAD; MCBH–4–MP–SS, STAINLESS STEEL/MOLDED NEOPRENE, SEALING; 340 BAR OPEN FACE, 600 BAR MATED.
IN–LINE; MCIL–4–FS, MOLDED NEOPRENE WITH CABLE. LOCKING SLEEVE; MCDLS–F, DELRIN.











ELECTRICAL OPTIONS/ SPECIFICATIONS

OUTPUT OPTION	OUTPUT	SUPPLY	
A	0.5 TO 4.5V RATIOMETRIC	5V	STANDARD
B	±5V	±15V	BUFFERED
C	0.5 TO 9.5V	24V	BUFFERED
D	±10V	±15V	BUFFERED
G	0.5 TO 4.5V	24V	BUFFERED
	SUPPLY CURRENT 12mA TYP. 20mA MAX.		BUFFERED
E	4 TO 20mA 2–WIRE	24V	BUFFERED
F	4 TO 20mA 3–WIRE SINK	24V	BUFFERED
H	4 TO 20mA 3–WIRE SOURCE	24V	BUFFERED

SINK VERSION OUTPUT COMPLIANCE 5–28V
SOURCE VERSION DRIVE 300Ω MAX TO 0V

MATING CONNECTOR (CODE 'J50' OR 'K50') SUPPLIED WITH 50cm MOULDED CABLE AS STANDARD.
4–CORE SCREENED: 0.5mm², ø7.5mm MAX. JACKET AND CORE INSULATION: EPDM.

CONNECTIONS:–

1	BLACK	OUTPUT
2	WHITE	0V
3	RED	BODY (OPTIONS: A, C, E–H) –Ve (OPTIONS: B OR D)
4	GREEN	+Ve
	SCREEN	NOT CONNECTED TO SENSOR

RANGE OF DISPLACEMENT FROM 0–15° TO 0–160° e.g. 76°, IN INCREMENTS OF 1°.

BODY MATERIAL: STAINLESS STEEL 316.

A	FIRST ISSUE.	RDS
B	RADIAL CONN ADDED - RAN1129.	PDM
C	CABLE COLOURS CORECTED - RAN1190	PDM
D	RANGE NOTE AMENDED ~ RAN1200	PDM

CE MAXIMUM WORKING DEPTH: 3500 METRES 350 BAR. WHERE THE FREE END OF THE CABLE IS TO BE TERMINATED IN A SUBMERGED POSITION, ADEQUATE SEALING MUST BE PROVIDED TO PROTECT CONNECTIONS.

DRAWINGS NOT TO BE CHANGED WITHOUT REFERENCE TO THE CHANGE PROCEDURE.
CHANGES TO PARTS USED IN INTRINSICALLY SAFE PRODUCT MUST BE APPROVED BY THE AUTHORISED PERSON
THIS IS AN UNCONTROLLED PRINT AND WILL NOT BE UPDATED.

A	15/09/15		CHECKED BY	X ±0.4
B	12/12/16		RDS	X.X ±0.2
C	14/06/17			X.XX ±0.1
D	13/09/17			DIMS mm
		DESCRIPTION		
		S623 350 BAR SUBMERSIBLE LARGE ANGLE TILT SENSOR		
SCALE 10mm		DRAWING NUMBER S623-11		REV D
				SHEET 1 OF 1